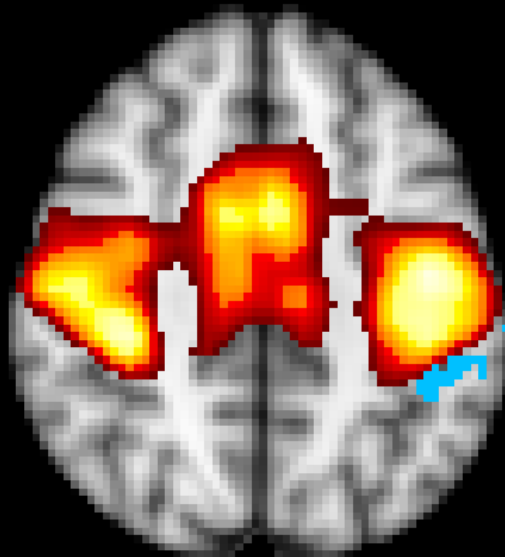
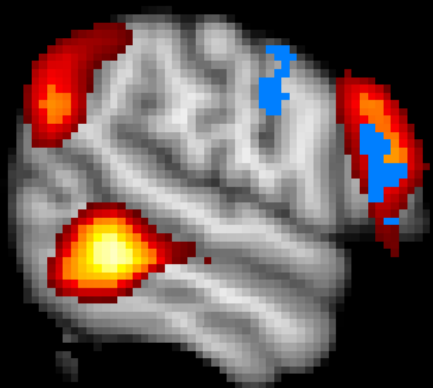
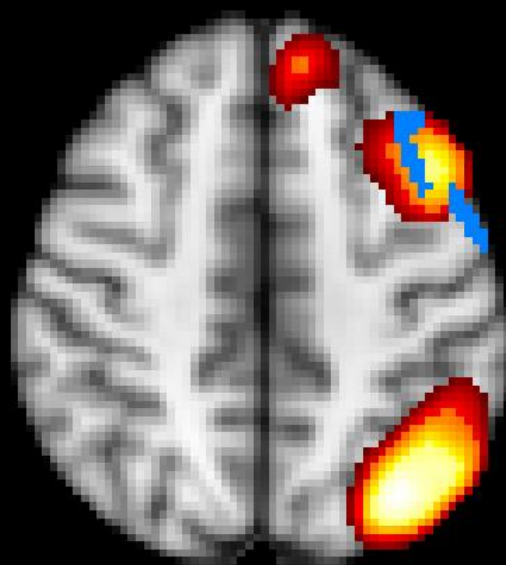


**A**

grasping task

 $y = -40$  $z = 46$ **B**

resting-state

 $x = -56$  $z = 46$