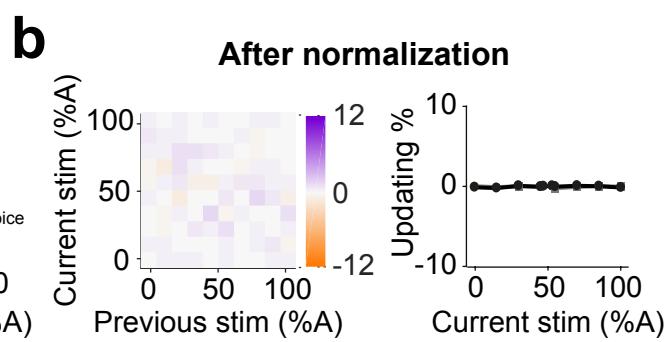
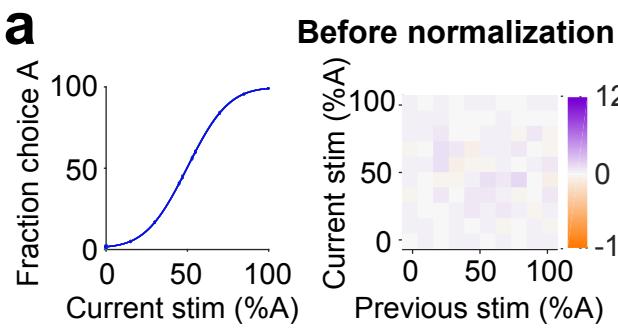
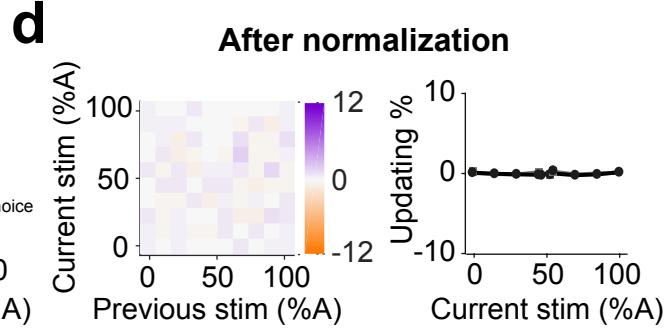
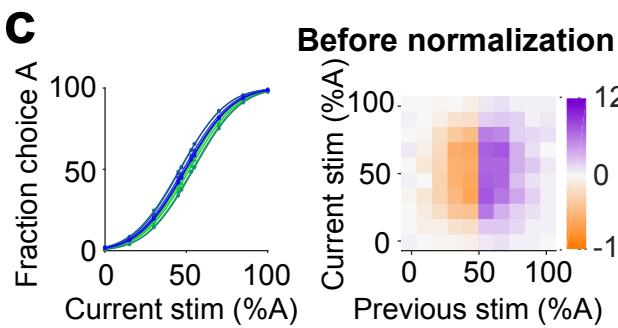


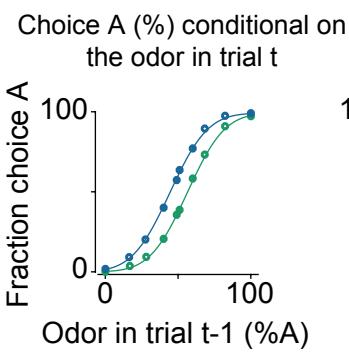
# Signal detection model with fixed decision boundary



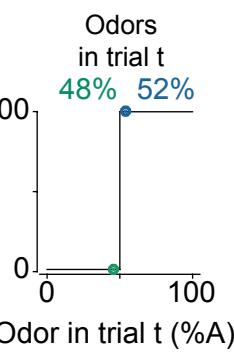
# Signal detection model with drifting decision boundary



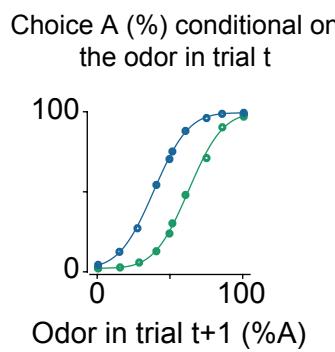
**e** trial t-1



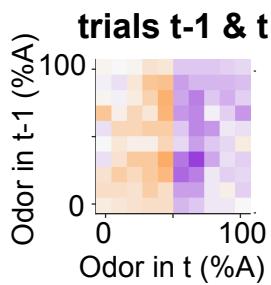
trial t



trial t+1



Same procedure as in (a)  
to get the heatmap



Point-by-point subtraction of heatmaps

(t+1 & t) - (t-1 & t)

