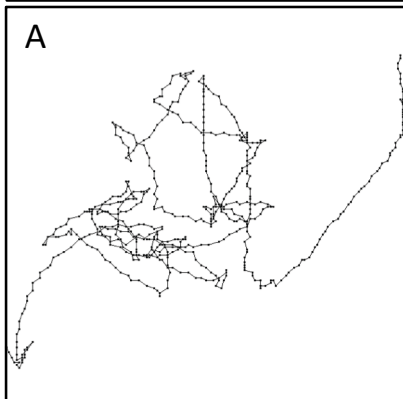
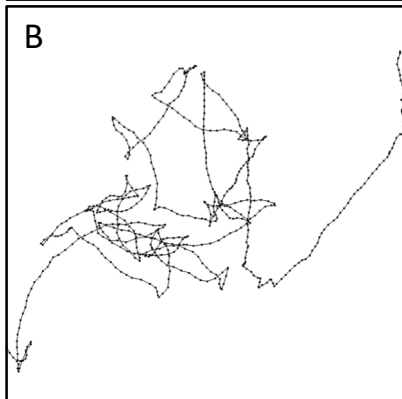


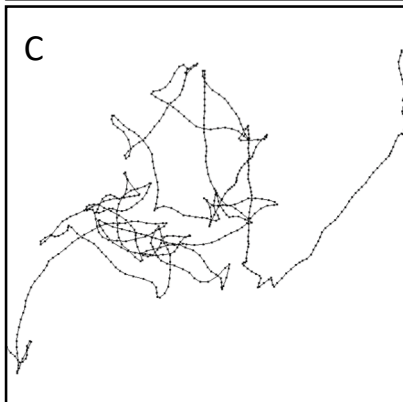
Raw unprocessed



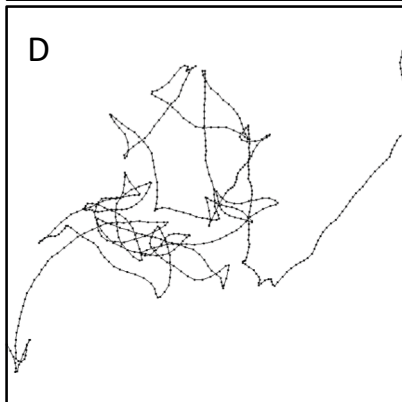
Position & velocity 0.5, covariance 1.0



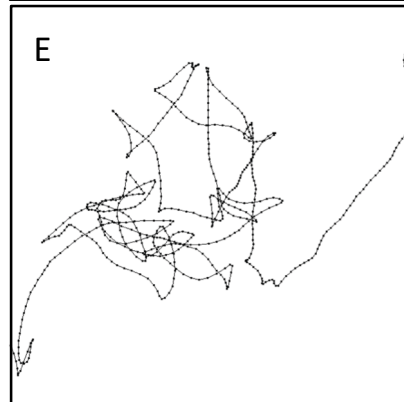
Position & velocity = 1.0



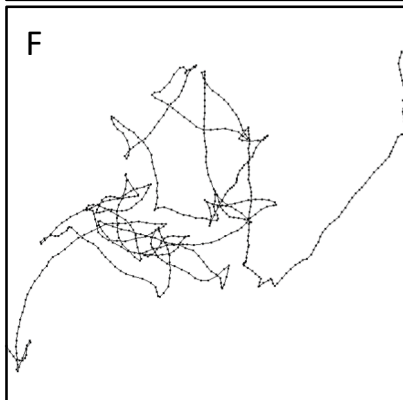
Position & velocity = 0.1



Position & velocity = 0.05



Minimum covariance = 2.0



Minimum covariance = 0.5



Minimum covariance = 0.1

