Strong confinement of active microalgae leads to inversion of vortex flow and enhanced mixing

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10 Abstract

- ¹¹ Microorganisms swimming through viscous fluids imprint their propulsion
- ¹² mechanisms in the flow fields they generate. Extreme confinement of these
- ¹³ swimmers between rigid boundaries often arises in natural and technological
- ¹⁴ contexts, yet measurements of their mechanics in this regime are absent. Here,
- ¹⁵ we show that strongly confining the microalga *Chlamydomonas* between two
- 16 parallel plates not only inhibits its motility through contact friction with the walls
- 17 but also leads, for purely mechanical reasons, to inversion of the surrounding
- vortex flows. Insights from the experiment lead to a simplified theoretical
- ¹⁹ description of flow fields based on a quasi-2D Brinkman approximation to the
- ²⁰ Stokes equation rather than the usual method of images. We argue that this
- $_{\mbox{\tiny 21}}$ $\,$ vortex flow inversion provides the advantage of enhanced fluid mixing despite
- ²² higher friction. Overall, our results offer a comprehensive framework for
- $_{\mbox{\tiny 23}}$ $\,$ analyzing the collective flows of strongly confined swimmers.
- 24

25 Introduction

Fluid friction governs the functional and mechanical responses of microorgan-26 isms which operate at low Reynolds number. They have exploited this friction 27 and developed drag-based propulsive strategies to swim through viscous flu-28 ids (Lauga and Powers, 2009; Pedlev and Kessler, 1992). Naturally, many studies 29 have elucidated aspects of the motility and flow fields of microswimmers in a vari-30 etv of settings that mimic their natural habitats (Elgeti et al., 2015; Bechinger et al., 31 2016: Denissenko et al., 2012: Bhattachariee and Datta, 2019). The self-propulsion 32 of microbes in crowded and strongly confined environments is one such setting, 33 encountered very commonly in the natural world as well as in controlled labora-34 torv experiments. Examples include microbial biofilms, bacteria- and algae-laden 35 porous rocks or soil (Qin et al., 2020; Hoh et al., 2016; Foissner, 1998; Bhattacharjee and 36 2019): parasitic infections in crowded blood streams and tissues (Heddergott et al., 37 2012); and biomechanics experiments using thin films and microfluidic channels 38 (Durham et al., 2009: Denissenko et al., 2012: Jeanneret et al., 2019: Ostapenko et al., 39 2018: Kurtuldu et al., 2011). Confined microswimmers are also fundamentally in-40 teresting as active suspensions (Brotto et al., 2013: Maitra et al., 2020) and there 41 are efforts to mimic these by chemical and mechanical means for applications in 42 nano- and microtechnologies (Duan et al., 2015; Temel and Yesilyurt, 2015). 43 The mechanical interaction of microswimmers with confining boundaries al-44 ters their motility and flow fields (Lauga and Powers, 2009; Brotto et al., 2013; 45 Mathiissen et al., 2016), leading to emergent self-organization in cell-cell coordi-46 nation (Riedel et al., 2005: Petroff et al., 2015), spatial distribution of cells (Tsang and Kar 47 2016: Rothschild, 1963), and ecological aspects such as energy expenditure, nutri-48 ent uptake, fluid mixing, transport and sensing (Lambert et al., 2013; Pushkin and Yeomo 49 2014). It is expected that steric interactions will dominate with increasing confine-50 ment at the swimmer-wall interface and that hydrodynamic screening by the con-51 fining wall will lead to recirculating flow patterns or vortices (Persat et al., 2015: 52 Mathiissen et al., 2016). 53 Among the abundant diversity of microswimmers, the unicellular and biflagel-54 lated algae Chlamydomonas reinhardtii (CR), with body diameter $D \approx 10 \,\mu$ m, are a 55

⁵⁶ versatile model system, widely used for understanding cellular processes such as

57 carbon fixation, DNA repair and damage, phototaxis, ciliary beating (Sasso et al.,

⁵⁸ 2018; Brumley et al., 2015; Choudhary et al., 2019; Mondal et al., 2020) and phys-

⁵⁹ ical phenomena of biological fluid dynamics (Goldstein, 2015; Brennen and Winet,

⁶⁰ **1977;** *Rafaï et al., 2010***)**. They are considered next-generation resources for wastew-

ater remediation and synthesis of biofuel, biocatalysts, and pharmaceuticals (Hoh et al.,

⁶² 2016; Khan et al., 2018). Recently, extreme confinement between two hard walls

⁶³ has been exploited to induce stress memory in CR cells towards enhanced biomass

64 production and cell viability (Min et al., 2014; Mikulski and Santos-Aberturas, 2021).

⁶⁵ Despite the existing and emerging contexts outlined above, knowledge about

⁶⁶ how rigid walls might modify the kinetics, kinematics, fluid flow and mixing, and

⁶⁷ theoretical description of a strongly confined microalga such as CR (or any other

⁶⁸ microswimmer) is scarce. All studies prior to ours have exclusively focused on

⁶⁹ the effect of boundaries on CR dynamics in PDMS chambers or thin fluid films of

⁷⁰ height $H \gtrsim 14\,\mu\text{m}$ (Jeanneret et al., 2019; Ostapenko et al., 2018; Guasto et al.,

2010), i.e., for weak confinement, D/H < 1.

Here, we present the first experimental measurements of the flagellar wave-72 form, motility and flow fields of strongly confined CR cells placed in between two 73 hard glass walls ~ 10 µm apart ($D/H \ge 1$, denoted 'H10 cells'), and infer from them 74 the effect of confinement on kinetics, energy dissipation and fluid mixing due to 75 the cells. We also measure the corresponding quantities for weakly confined 76 cells placed in glass chambers of height $H = 30 \,\mu\text{m} (D/H \sim 0.3, \text{ denoted 'H30})$ 77 cells') for comparison. We find that the cell speed decreases significantly and the 78 trajectory tortuosity increases with increasing confinement as we go from H30 to 79 H10 cells. 80

Surprisingly, the beat-cycle averaged experimental flow field of strongly con-81 fined cells has opposite flow vorticity to that expected from the screened ver-82 sion of bulk flow (Drescher et al., 2010; Guasto et al., 2010). This counterintu-83 itive result comes about because the close proximity of the walls greatly sup-84 presses the motility of the organism and, consequently, the thrust force of the 85 flagella is balanced primarily by the non-hydrodynamic contact friction from the 86 walls. The reason being that the flagellar thrust is largely unaffected by the walls. 87 whereas the hydrodynamic drag on the slowly moving cell body is readily seen to 88 be far smaller. Understandably, theoretical predictions from the source-dipole 89

description of strongly confined swimmers do not account for this vortex flow ۹N inversion because they include only hydrodynamic stresses (Brotto et al., 2013; 91 *Mathijssen et al., 2016*). We complement our experimental results with a sim-92 ple theoretical description of the strongly confined microswimmer flows using 93 a guasi-2D steady Brinkman approximation to the Stokes equation (Brinkman, 94 1949), instead of the complicated method of recursive images using Hankel trans-95 forms (Liron and Mochon, 1976; Mathijssen et al., 2016). Solving this equation, 96 we demonstrate that the vortex flow inversion in strong confinement is well-97 described as arising from a pair of like-signed force densities localized with a 98 Gaussian spread around the approximate flagellar positions rather than the conventional three overall neutral point forces for CR (Drescher et al., 2010). We also 100 show that under strong confinement there is enhanced fluid transport and mix-101 ing despite higher drag due to the walls. 102

103 Results

104 **Experimental System**

Synchronously grown wild-type CR cells (strain CC 1690) swim in a fluid medium 105 using the characteristic breaststroke motion of two $\sim 11 \,\mu m$ long anterior flagella 106 with beat frequency $v_h \sim 50 - 60$ Hz. These cells are introduced into rectangular 107 guasi-2D chambers (area, $18 \text{ mm} \times 6 \text{ mm}$) made up of a glass slide and coverslip 108 sandwich with double tape of thickness $H = 10/30 \,\mu\text{m}$ as spacer. Passive 200 nm 109 latex microspheres are added as tracers to the cell suspension for measuring 110 the fluid flow using particle-tracking velocimetry (PTV). We use high-speed phase-111 contrast imaging at ~ 500 frames/second and 40X magnification to capture flag-112 ellar waveform and cellular and tracer motion at a distance H/2 from the solid 113 walls. The detailed experimental procedure is described in the Materials and 114 Methods section. 115

Mechanical equilibrium of confined cells

117 The net force and torque on microswimmers, together with the ambient medium

- and boundaries, can be taken to be zero as gravitational effects are negligible in
- the case of CR for the range of length scales considered (*Drescher et al., 2010*;
- Brennen and Winet, 1977; Pedley and Kessler, 1992; Elgeti et al., 2015; Mathijssen et al.,



Figure 1. Cell size affects forces acting on confined microswimmers. Schematics of the forces exerted by a *Chlamydomonas* cell (green) swimming along the *x*-axis in between two glass plates separated by height, *H* under (**A**) weak confinement where the cell's body diameter, D < H and (**B**) strong confinement where $D \gtrsim H$. Solid arrows represent local forces exerted by the cell on the surrounding medium. *F*_{th} and *F*_{hd} are the propulsive thrust distributed equally between the two flagella and hydrodynamic drag due to the cell body, respectively. *F*_{cf} is the contact friction with the strongly confining walls (B). Time lapse images of CR cells swimming in a quasi-2D chamber of height $H = 10 \,\mu\text{m}$ with (**C**) synchronously beating flagella with $v_b \sim 39 \,\text{Hz}$ ($D \sim 13.2 \,\mu\text{m}$); (**D**) asynchronously beating flagella ($D \sim 9.9 \,\mu\text{m}$); and (**E**) paddler type flagellar beat ($D \sim 9.7 \,\mu\text{m}$). The cell bodies in (D) and (E) wobble due to their irregular flagellar beat pattern and are called 'Wobblers'. (**F**) Histogram of cell body diameter in the chamber of $H = 10 \,\mu\text{m}$ (Number of cells, N = 70). Synchronously beating cells (N = 34) typically have larger diameter than Wobblers (N = 36) and thus the H10 Synchronous cells with $D/H \gtrsim 1$ are strongly confined.

Figure 1-source data 1. Source data for Figure 1F.

2016). The two local forces exerted by any dipolar microswimmer on the sur-121 rounding fluid are flagellar propulsive thrust F_{th} and cell body drag F_{hd} . They bal-122 ance each other completely for any swimmer in an unbounded medium (Lauga and Pow 123 2009; Goldstein, 2015) and approximately in weak confinement between two 124 hard walls (Figure 1A). In these regimes, CR is the classic example of an active 125 puller where the direction of force dipole due to thrust and drag are such that 126 the cell draws in fluid along the propulsion axis (x-axis in *Figure 1*A) and ejects 127 it in the perpendicular plane (Lauga and Powers, 2009). CR is described well by 128 three point forces or Stokeslets (Drescher et al., 2010) as in Figure 1A because 129 the thrust is spatially extended and distributed equally between the two flagella. 130 However, microswimmers in strong confinement between two closely spaced 131 hard walls, $D/H \ge 1$, are in a regime altogether different from bulk because the 132 close proximity of the cells to the glass walls results in an additional drag force 133 F_{cf} (Figure 1B). Therefore, the flagellar thrust is balanced by the combined drag 134 due to the cell body and the strongly confining walls (Figure 1B). 135

Size polydispersity, confinement heterogeneity, and consequences for flagellar waveform and motility

We define the degree of confinement of the CR cells as the ratio D/H of cell 138 body diameter to chamber height. CR cells in chambers of height $H = 30 \,\mu\text{m}$ are 139 always in weak confinement as the cell diameter varies within $D \sim 8 - 14 \,\mu\text{m} <$ 140 $H_{\rm c}$ However, this dispersity in cell size becomes significant when CR cells are 141 swimming within quasi-2D chambers of height, $H = 10 \,\mu m$. Here, the diameter 142 of individual cell is crucial in determining the character - weak or strong - of 143 the confinement and, as a consequence, the forces acting on the cell. Below. 144 we illustrate how the cell size determines the type of confinement in this regime 145 through measurements of flagellar waveform and cell motility. 146

¹⁴⁷ CR cells confined to swim in $H = 10 \,\mu$ m chambers show three kinds of flag-¹⁴⁸ellar waveform: (a) synchronous breaststroke and planar beating of flagella in-¹⁴⁹terrupted by intermittent phase slips ('H10 Synchronous', *Figure 1*C, *Video 1*); (b) ¹⁵⁰asynchronous and planar flagellar beat over large time periods (*Figure 1*D, *Video 2*); ¹⁵¹and (c) a distinctive paddling flagellar beat wherein flagella often wind around ¹⁵²each other and paddle irregularly anterior to the cell with their beat plane ori-



Figure 2. Cell motility in confinement. Representative trajectories of CR cells in (**A**) $H = 30 \,\mu\text{m}$ (N = 25), (**B**) $H = 10 \,\mu\text{m}$, Wobblers (N = 13); (**C**) $H = 10 \,\mu\text{m}$, Synchronous cells (N = 17). All of these trajectories lasted for 8.2 s and their initial positions are shifted to origin. (**D**), (**E**) and (**F**) are the zoomed in trajectories of (A), (B) and (C), respectively. (**G**) Cell speed (circles) and tortuosity of trajectories (squares) as a function of the degree of confinement, D/H (N = 52, 35, 23 for H30, H10 Wobbler and H10 Synchronous, respectively). The error bars in the plot correspond to standard deviation in diameter (x-axis), cell speed and tortuosity (y-axes) due to the heterogeneous population of cells.

Figure 2-source data 1. Source data for Figure 2A.
Figure 2-source data 2. Source data for Figure 2B.
Figure 2-source data 3. Source data for Figure 2C.
Figure 2-source data 4. Source data for Figure 2G.

ented away from the x - y plane (*Figure 1*E, *Video 2*). While both synchronous 153 and asynchronous beats are typically observed for CR in bulk (Polin et al., 2009) 154 and weak confinement of 30 µm, the paddler beat is associated with calcium-155 mediated mechanosensitive shock response of the flagella to the chamber walls 156 (Fujiu et al., 2011). The cell body wobbles for both asynchronous and paddler 157 beat of cells (Figure 1D & E) and often the flagellar waveform in a single CR 158 switches between these two kinds (Video 2). Hence, we collectively call them 159 'H10 Wobblers' (Qin et al., 2015). 160

We correlate the Synchronous and Wobbler nature of cells to their body diameter (*Figure 1*F). The mean projected diameter in the image plane of Synchronous cells ($D = 12.28 \pm 0.94 \,\mu$ m, Number of cells, N = 34) is larger than that of Wobblers

 $(D = 9.92 \pm 0.85 \,\mu\text{m}, N = 36)$. Hence, the former's cell body is squished and strongly 164 confined in $H = 10 \,\mu\text{m}$ chamber in comparison with that of the latter. This leads 165 to planar swimming of Synchronous cells, whereas Wobblers tend to spin about 166 their body axis and trace out a near-helical trajectory which is a remnant of its 167 behaviour in the bulk. Thus, the Wobblers likely compromise their flagellar beat 168 into asynchrony and/or paddling over long periods, as a shock response, due 169 to frequent mechanical interactions with the solid boundaries while rolling and 170 vawing their cell body (Fujiu et al., 2011; Choudharv et al., 2019). 171

The motility of CR cells in $H = 30 \,\mu\text{m}$ is similar to that in bulk and has the sig-172 nature of back-and-forth cellular motion due to the recovery and power strokes 173 of the flagella (*Figure 2*A.D). As confinement increases, the drag on the cells due 174 to the solid walls increases and they trace out smaller distances with increasing 175 twists and turns in the trajectory (*Figure 2*A-F). These phenomena can be quanti-176 tatively characterized by cell speed and trajectory tortuosity (Materials and Meth-177 ods) as a function of the degree of confinement of the cells (*Figure 2*G). Cellular 178 speed decreases and tortuosity of trajectories increases with increasing confine-179 ment as we go from H30 \rightarrow H10 Wobblers \rightarrow H10 Synchronous cells. Notably, the 180 cell speed u decreases by 96% from H30 ($\langle u^{30} \rangle = 122.14 \pm 31.59 \ \mu m/s$, N = 52) to 181 H10 Synchronous swimmers ($\langle u^{10} \rangle = 4.07 \pm 2.88 \ \mu m/s$, N = 23). Henceforth, we 182 equivalently refer to the H10 Synchronous CR as 'strongly confined' or 'H10' cells 183 $(D/H \ge 1)$ and the H30 cells as 'weakly confined' (D/H < 1). 184

¹⁸⁵ We also note that the flagellar beat frequency of the strongly confined cells, ¹⁸⁶ $v_b^{10} \approx 51.58 \pm 7.62$ Hz (averaged over 210 beat cycles for N = 20) is similar to that ¹⁸⁷ of the weakly confined ones, $v_b^{30} \approx 55.27 \pm 8.22$ Hz (averaged over 194 beat cycles ¹⁸⁸ for N = 20). This is because even in the 10 µm chamber where the CR cell body is ¹⁸⁹ strongly confined, the flagella are beating far from the walls (~ 5 µm) and almost ¹⁹⁰ unaffected by the confinement.

¹⁹¹ Video 1. Video of a strongly confined Chlamydomonas cell swimming with syn-¹⁹² chronous beat in presence of tracers. High-speed video microscopy of a strongly con-¹⁹³ fined swimmer (synchronously beating *Chlamydomonas* cell in $H = 10 \,\mu\text{m}$ chamber) in ¹⁹⁴ presence of tracer particles at 500 frames/s. This phase-contrast video clearly shows the ¹⁹⁵ synchronous breaststroke and planar beating of flagella with intermittent phase slips. ¹⁹⁶ This is the representative cell whose flow field is shown in *Figure 3*C. The direction of

Video 2. Video of wobbling Chlamydomonas cells with asynchronous or paddling 198 **flagellar beat.** Flagellar waveform of *Chlamydomonas* cells in $H = 10 \,\mu\text{m}$ chamber with 199 wobbling cell body i.e., H10 Wobblers. The video is divided into 3 parts. The first part 200 shows the asynchronous and planar flagellar beat of a cell which leads to a wobbling 201 motion of the cell body. The second part shows the distinctive paddling flagellar beat 202 of a cell, anterior to the cell body. Here, the flagellar beat plane is perpendicular to the 203 imaging x - y plane and one of the flagella is mostly out of focus. In both these cases, 204 the cell bodies wobble due to their irregular flagellar beat pattern. The third part shows 205 a representative H10 Wobbler which switches from paddling beat to an asynchronous 206 one. 207

208 Experimental flow fields

We measure the beat-averaged flow fields of H30 and H10 CR cells to systemati-209 cally understand the effect of strong confinement on the swimmer's flow field. 210 We determine the flow field for H30 cells only when their flagellar beat is in 211 the x - y plane (*Video 3*) for appropriate comparison with planar H10 swimmers. 212 Figure 3A shows the velocity field for H30 cells obtained by averaging ~ 178 beat 213 cvcles from 32 cells. It shows standard features of an unbounded CR's flow field 214 (Drescher et al., 2010; Guasto et al., 2010), namely far-field 4-lobe flow of a puller, 215 two lateral vortices at 8-9 µm from cell's major axis and anterior flow along the 216 swimming direction till a stagnation point, 21 µm from the cell centre (*Figure 3*B). 217 These near-field flow characteristics are guite well explained theoretically by a 3-218 bead model (Jibuti et al., 2017; Friedrich and Jülicher, 2012; Bennett and Golestanian, 219 2013) or a 3-Stokeslet model (Drescher et al., 2010), where the thrust is distributed 220 at approximate flagellar positions between two Stokeslets of strength (-1/2, -1/2)221 balanced by a + 1 Stokeslet due to viscous drag on the cell body (*Figure 1*A). 222 The flow field of a representative H10 swimmer ($u = 5.67 \pm 1.57 \ \mu m/s$, $v_b \sim$ 223 42.67 ± 2.24 Hz) is shown in *Figure 3C*, averaged over ~ 328 beat cycles. Strikingly, 224 the vortices contributing dominantly to the flow in this strongly confined geom-225 etry are opposite in sign to those in the bulk (Drescher et al., 2010) or weakly 226 confined case (H30, Figure 3A). This 2-lobed flow is distinct from expectations 227 based on the screened version of the bulk or 3-Stokeslet flow, which is 4-lobed 228



Figure 3. Experimental flow fields of CR cells in weak and strong confinement.

Experimentally measured, beat-averaged flow fields in the x - y plane of synchronously beating CR cells swimming in (**A**) $H = 30 \,\mu$ m, (**C**) $H = 10 \,\mu$ m. Black arrows on the cell body indicate that the cells are swimming to the right. Solid black lines indicate the streamlines of the flow in lab frame. The colorbars represent flow magnitude, v. (**B**) and (**D**) denote the speed variation in (A) and (C), respectively, along anterior, posterior and lateral to the cell (where the vortices are present). Distances along anterior and posterior are measured along horizontal lines from the cell centre (0,0); whereas the lateral (vortex) distances are measured along the vertical line passing through (x, y) = (2,0) for (B) and (8,0) for (D), respectively.

Figure 3–Figure supplement 1. Expected flow fields of a strongly confined CR using conventional theoretical approaches.

Figure 3-source data 1. Source data for Figure 3A.

Figure 3-source data 2. Source data for Figure 3C.

(Figure 3-Figure Supplement 1A). Importantly, the far-field flow resembles a 2D 229 source dipole pointing opposite to the swimmer's motion, which is entirely differ-230 ent from that produced by the standard source dipole theory of strongly confined 231 swimmers (Figure 3-Figure Supplement 1B) (Brotto et al., 2013; Mathijssen et al., 232 2016: leanneret et al., 2019). This is because the source-dipole treatment does 233 not consider the possibility that the cells are squeezed by the walls, or in other 234 words, it does not account for contact friction (Brotto et al., 2013; Mathijssen et al., 235 2016). Other significant differences from the bulk flow include front-back flow 236 asymmetry, opposite flow direction posterior to the cell, distant lateral vortices 237 (20 µm) and closer stagnation point (11 µm) (Figure 3D). All other H10 Synchronous 238 swimmers, including the slowest ($u \sim 0.15 \,\mu\text{m/s}$) and the fastest ($u \sim 14 \,\mu\text{m/s}$) cells, 220 show similar flow features. Even though the flow fields of H30 and H10 cells look 240 strikingly different, the viscous power dissipated through the flow fields is nearly 241 the same (Appendix 1.1). 242

A close examination suggests that the vortex contents of the flow fields of *Figure 3*A (H30) and *Figure 3*C (H10) are mutually compatible. The large vortices flanking the rapidly moving CR in H30 are shrunken and localized close to the cell body in H10 due to the greatly reduced swimming speed. The frontal vortices generated by flagellar motion now fill most of the flow field in H10. Generated largely during the power stroke of flagella, they are opposite in sense to the vortices produced by the moving cell body.

Video 3. Video of a weakly confined Chlamydomonas cell swimming in presence of 250 tracers. High-speed video microscopy of a weakly confined *Chlamydomonas* cell swim-251 ming in $H = 30 \, \mu m$ chamber in presence of tracer particles at 500 frames/s. This video 252 shows the natural motility of cells in bulk where they spin about their body axis. The 253 video starts with the cell and its flagella beating in the image plane. At $\sim 90 - 180$ ms, the 254 flagellar beat of the cell is out of the image plane, when the cell body is rotating about 255 its axis. The flow field is calculated only when the flagellar beat of the H30 cell is in the 256 image plane, i.e. for 0 - 90 ms and 180 - 252 ms for this particular video. 257

258 Force balance on confined cells

In an unbounded fluid, the thrust F_{th} exerted by the flagellar motion of the cell

balances the hydrodynamic drag F_{hd} on the moving cell body (*Figure 1*A). We as-

sume this balance holds for the case of weak confinement (H30) as well. We estimate $|F_{hd}| = 3\pi\eta Du$ as the Stokes drag on a spherical cell body of diameter $D \simeq$ 10 µm moving at speed *u* through a fluid of viscosity $\eta = 1$ mPa s (*Goldstein, 2015*) which in the regime of weak confinement (H30), for a cell speed $u^{30} \approx 120$ µm/s, is $F_{hd}^{30} \approx 11.31$ pN \hat{x} , so that the corresponding thrust force $F_{th}^{30} \approx -11.31$ pN \hat{x} .

Given that CR operates at nearly constant thrust since $u \propto \eta^{-1}$ (**Qin et al., 2015**; 266 Rafaï et al., 2010) and that the flagella of the H10 cell are beating far from the 267 walls (~ 5 µm) with beat frequency and waveform similar to that of the H30 cell 268 (Video 1 and Video 3), we take the flagellar thrust force in strong confinement 269 to be $F_{th}^{10} \approx F_{th}^{30} \approx -11.31 \,\text{pN}\,\hat{x}$ as in weak confinement. This thrust is balanced 270 by the total drag on the cell body. The cell speed, $u^{10} \approx 4\,\mu\text{m/s}$, is down by a 271 factor of 30, and so is the hydrodynamic contribution to the drag if we assume 272 the flow is the same as for the H30 geometry. Even if we take into account the 273 tight confinement, and thus assume that the major hydrodynamic drag comes 274 (Brotto et al., 2013; Persat et al., 2015; Bhattacharya et al., 2005) from a lubri-275 cating film of thickness $\delta = (H - D)/2 \ll D$ between the cell and each wall, the 276 enhancement of drag due to the fluid, logarithmic in δ/D (**Bhattacharya et al.**, 277 **2005:** Ganatos et al., 1980), cannot balance thrust for any plausible value of δ . 278

The above imbalance drives the vortex flow inversion observed in Figure 3C, 279 as will be shown later theoretically, and implies that the drag is dominated by the 280 direct frictional contact between the cell body and the strongly confining walls, 281 which we denote by F_{cf} . Force balance on the fluid element and rigid walls en-282 closing the CR in strong confinement requires $F_{th}^{10} + F_{hd}^{10} + F_{cf}^{10} = 0$ (*Figure 1*B). 283 We know that the hydrodynamic drag under strong confinement is greater than 284 0.38 pN (Stokes drag at $u^{10} \approx 4 \,\mu$ m/s), but lack a more accurate estimate as we 285 do not know the thickness δ of the lubricating film. We can therefore say that 286 the contact force $F_{cf}^{10} \lesssim 10.93 \text{ pN} \hat{x}$. Thus the flagellar thrust works mainly against 287 the non-hydrodynamic contact friction from the walls as expected due to the ex-288 tremely low speed of the strongly confined swimmer. 289

²⁹⁰ Theoretical model of strongly confined flow

We begin by using the well-established far-field solution of a parallel Stokeslet
 between two plates by Liron & Mochon in an attempt to explain the strongly con-



Figure 4. Theoretical flow fields in strong confinement. Theoretically computed flow fields for (**A**) 2 Stokeslets and (**C**) 2-Gaussian forces, both positioned at $(6, \pm 11) \mu m$ (red arrows) using the quasi-2D Brinkman equation for $H = 10 \mu m$ at the z = 0 plane. The colorbars represent flow magnitudes normalised by their maximum, v_{nor} . (**B**) and (**D**) Comparison of normalised experimental flow of the CR in $H = 10 \mu m$ (*Figure 3*C) with theoretical flow fields (A) and (C), respectively along representative radial distances, r, from the cell centre as a function of polar angle. Inset of (B) shows the convention used for polar angle. Plots for each r denote the flow magnitudes for those grid points which lie in the radial gap $(r, r + 1) \mu m$; $r (\mu m) = 7$ (yellow), 13 (blue), 20 (magenta), 30 (green). **Figure 4-Figure supplement 1.** Schematic of velocity profile along the confining direc-

tion.

Figure 4–Figure supplement 2. Comparison in the direction of flow fields between experiment and theory.

Figure 4-Figure supplement 3. Theoretical flow field in weak confinement.

Figure 4-source data 1. Source data for Figure 4A.

Figure 4-source data 2. Source data for Figure 4C.

fined CR's flow field (*Liron and Mochon, 1976*). However, the theoretical flow of Liron & Mochon decays much more rapidly than the experimental one and does not capture the vortex positions and flow variation in the experiment (*Appendix 1.2* and *Appendix 1—Figure 1*). This is because the Liron & Mochon approximation to the confined Stokeslet flow is itself singular and also the far-field limit of the full analytical solution, so it cannot be expected to accurately explain the near-field characteristics of the experimental flow (*Liron and Mochon, 1976*).

We therefore start afresh from the incompressible 3D Stokes equation, $-\nabla p(\mathbf{r})$ + 300 $\eta \nabla^2 \mathbf{v}(\mathbf{r}) = 0, \ \nabla \cdot \mathbf{v}(\mathbf{r}) = 0$, where p and v are the fluid pressure and velocity 301 fields, respectively. Next, we formulate an effective 2D Stokes equation and 302 find its point force solution. In a quasi-2D chamber of height H_i , we consider 303 an effective description of a CR swimming in the z = 0 plane of the coordi-304 nate system with the first Fourier mode for the velocity profile along z_i , satis-305 fying the no-slip boundary condition on the solid walls, $v(x, y, z = \pm H/2) = 0$ 306 (Figure 4-Figure Supplement 1). Therefore, the flow velocity varies as v(x, y, z) =307 $v^0(x, y)\cos(\pi z/H)$ (Figure 4-Figure Supplement 1), where $v^0 = (v_x, v_y)$ is the flow 308 profile in the swimmer's x - y plane that is experimentally measured in *Figure 3* 309 (Fortune et al., 2021). Substituting this form of velocity field in the Stokes equa-310 tion we obtain its quasi-2D Brinkman approximation (Brinkman, 1949), which for 311 a point force of strength *F* at the z = 0 plane, is 312

$$-\nabla_{xy} p(\mathbf{r}) + \eta \left(\nabla_{xy}^2 - \frac{\pi^2}{H^2}\right) \boldsymbol{v}(\mathbf{r}) + F\delta(\mathbf{r}) = 0, \quad \nabla_{xy} \cdot \boldsymbol{v}(\mathbf{r}) = 0$$
(1)

where *p* and $v \equiv v_0$ are the pressure and fluid velocity in the x - y plane and $\nabla_{xy} = \partial_x \hat{x} + \partial_y \hat{y}$. We Fourier transform the above equation in 2D and invoke the orthogonal projection operator $O_k = 1 - \hat{k}\hat{k}$ to annihilate the pressure term and obtain the quasi-2D Brinkman equation in Fourier space

$$v_k = \frac{O_k \cdot F}{\eta \left(k^2 + \frac{\pi^2}{H^2}\right)} \tag{2}$$

³¹⁷ We perform inverse Fourier transform on *Equation 2* in 2D for a Stokeslet ³¹⁸ oriented along the *x*-direction, $F = F \hat{x}$ to obtain its flow field v(r) at the z = 0³¹⁹ plane (*Appendix 1.3*). This solution is identical to the analytical closed-form ex-³²⁰ pression of *Pushkin and Bees (2016)*. We have already shown that superpos-

ing our Brinkman solution for the conventional three point forces at cell cen-321 tre and flagellar positions of CR, which leads to the effective 3-Stokeslet model 322 in 2D, is an inappropriate description of the strongly confined flow (Figure 3-323 Figure Supplement 1A). This is not surprising at this point because the force im-324 balance between the flagellar thrust and hydrodynamic cell drag suggests that 325 the cell is nearly stationary compared to the motion of its flagella. We utilize 326 this experimental insight by superposing only two Stokeslets of strength $-1/2\hat{x}$ 327 each at approximate flagellar positions $(x_f, \pm y_f) = (6, \pm 11) \mu m$ to find qualitatively 328 similar streamlines and vortex flows (Figure 4A) as that of the experimental flow 329 field (Figure 3C). However, this theoretical '2-Stokeslet Brinkman flow' (Figure 4A) 330 decays faster than the experiment as shown in the guantitative comparison of 331 these two flows in Figure 4B and Figure 4-Figure Supplement 2, A and B. The 332 root mean square deviation (RMSD) between these two flows in v_x , v_y and |v|333 are 20.3%, 14.2% and 22.6%, respectively (see Materials and Methods for RMSD 334 definition). 335

With the experimental streamlines and vortices well described by a 2-Stokeslet 336 Brinkman model, we now explain the slower flow variation in experiment. Strongly 337 confined experimentally observed flow is mostly ascribed to the flagellar thrust. 338 as described above. Clearly, a delta-function point force will not be adequate 339 to describe the thrust generated by flagellar beating as they are slender rods of 340 length $L \sim 11 \,\mu\text{m}$ with high aspect ratio. We, therefore, associate a 2D Gaussian 3/11 source $g(\mathbf{r}) = \frac{e^{-r^2/2\sigma^2}}{2\pi\sigma^2}$ of standard deviation σ , to **Equation 1** instead of the point-342 source $\delta(\mathbf{r})$, in a manner similar to the regularized Stokeslet approach (*Cortez et al.*. 343 2005). Thus, the guasi-2D Brinkman equation in Fourier space (Equation 2) for a 344 Gaussian force Fg(r) becomes, 345

$$v_{k} = \frac{O_{k} \cdot F}{\eta \left(k^{2} + \frac{\pi^{2}}{H^{2}}\right)} e^{-k^{2} \sigma^{2}/2} \quad .$$
(3)

Superposing the inverse Fourier transform of the above equation for two sources of $\mathbf{F} = (-1/2, -1/2) \hat{\mathbf{x}}$ at $(x_f, \pm y_f) = (6, \pm 11)$ um with $\sigma \sim L/2 = 5 \,\mu$ m, we obtain the theoretical flow shown in *Figure 4*C. RMSD in v_x , v_y and $|\mathbf{v}|$ between this theoretical flow and those of the experimental one (*Figure 3*C) are 7.8%, 9% and 8.3%, respectively. Comparing these two flows along representative radial dis-

tances from the cell centre as a function of polar angle show a good agreement 351 (Figure 4D and Figure 4-Figure Supplement 2, C and D). Notably, Figure 4C, i.e., 352 the '2-Gaussian Brinkman flow', has captured the flow variation and most of the 353 experimental flow features accurately. Specifically, these are the lateral vortices 354 at 20 µm and an anterior stagnation point at 13 µm from cell centre. The only 355 limitation of this theoretical model is that it cannot account for the front-back 356 asymmetry of the strongly confined flow, as is evident from Figure 4C for the 357 polar angles 0 or 2π and π which correspond to front and back of the cell, re-358 spectively. This deviation is more pronounced in the frontal region as the cell 359 body squashed between the two solid walls mostly blocks the forward flow from 360 reaching the cell posterior. Thus, the no-slip boundary on the cell body needs 361 to be invoked to mimic the front-back flow asymmetry, which is a more involved 362 analysis due to the presence of multiple boundaries and can be addressed in a 363 follow-up study. 364

Now that we have explained the flow field of CR in strong confinement, we 365 test our quasi-2D Brinkman theory in weak confinement, $H = 30 \,\mu$ m, where the 366 thrust and drag forces almost balance each other. Hence, we use the conven-367 tional 3-Stokeslet model for CR, but with a Gaussian distribution for each point 368 force. We, therefore, superpose the solution of *Equation 3* for 3-Gaussian forces 369 representing the cell body and two flagella in $H = 30 \,\mu m$. The resulting flow 370 field (Figure 4-Figure Supplement 3) matches qualitatively with the experimental 371 flow field of CR in weak confinement (Figure 3A). This deviation is expected in 372 weak confinement, $D/H \sim 0.3$, because the quasi-2D theoretical approximation 373 is mostly valid at $D/H \gtrsim 1$, even though RMSD in v_x , v_y and |v| remain in the low 374 range at 11.4%, 11.2% and 13.8%, respectively. 375

Together, the experimental and theoretical flow fields show that the contact friction from the walls reduces the force-dipolar swimmer in bulk or weak confinement (H30) to a force-monopole one in strong confinement (H10).

³⁷⁹ Enhancement of fluid mixing in strong confinement

³⁸⁰ The photosynthetic alga CR feeds on dissolved inorganic ions/molecules such as

- ³⁸¹ phosphate, nitrogen, ammonium, and carbon dioxide from the surrounding fluid
- in addition to using sunlight as the major source of energy (*Tam and Hosoi, 2011*;



Figure 5. Correlation in fluid flow and tracer displacements. (**A**) Normalised radial velocity-velocity correlation function, $C_{vv}(R)$, of flow fields in *Figure 3*A,C and *Figure 4*C. The dashed vertical lines denote the correlation length scales for the flows, $\lambda = 9.6 \,\mu$ m (H30) and 13.2 μ m (H10, both experiment and theory), where the correlation function decays to 1/e (horizontal dashed line). (**B**) and (**C**) Snapshots showing passive tracer trajectories (coloured) due to a CR cell (white) swimming along the black dashed arrow in $H = 30 \,\mu$ m and $H = 10 \,\mu$ m, respectively. The H30 swimmer ($u = 121 \,\mu$ m/s) passes through the field of view within 1.3 s whereas the H10 cell ($u = 3 \,\mu$ m/s) traces a semicircular trajectory staying in the field of view for the recording time of 8.2 s. The tracer trajectories are colour coded, according to the colorbar below, based on their maximum displacement, Δr_{trer} , during a fixed lag time of $\Delta t = 0.2 \,\text{s}$ (~ 10 flagellar beat cycles). Scale bars, 15 μ m.

Figure 5-Figure supplement 1. Mean squared displacement (MSD) of tracers.

Figure 5-source data 1. Source data for Figure 5A.

Kiørboe, 2008). Importantly, nitrogen and carbon are limiting macronutrients to 383 algal growth and metabolism (Khan et al., 2018: Short et al., 2006: Kiørboe, 2008). 384 For example, dissolved carbon dioxide in the surrounding fluid contains the car-385 bon source essential for photosynthesis and acts as pH buffer for optimum al-386 gal growth. It is widely known that flagella-generated flow fields help in uni-387 form distribution of these dissolved solute molecules through fluid mixing and 388 transport which have a positive influence on the nutrient uptake of osmotrophs 389 like CR (Kiørboe, 2008: Tam and Hosoi, 2011: Ding et al., 2014: Short et al., 2006: 300 Leptos et al., 2009; Kurtuldu et al., 2011). This is even more important for the 391 strongly confined CR cells as they cannot move far enough to outrun diffusion of 392 nutrient molecules because of slow swimming speed. 303

We first calculate the flow-field based Péclet number, $Pe = V l_V / D_S$ where 394 V and l_V are the flow-speed and diameter of the flagellar vortex, and D_S is the 395 solute diffusivity in water, as the standard measure to characterize the relative 396 significance of advective to diffusive transport. Using the experimentally mea-397 sured flow data from Figure 3 and $D_s \approx 10^{-9} \, \text{m}^2/\text{s}$ (Shapiro et al., 2014; Kiørboe, 398 2008; Tam and Hosoi, 2011), we compute the Péclet numbers for the weakly and 399 strongly confined cell to be $Pe^{30} \approx 0.5$ and $Pe^{10} \approx 2$, respectively (see Appendix 1— 400 Table 1 and Appendix 1.4). These numbers suggest that flow-field-mediated ad-401 vection does not completely dominate, but nevertheless can play a role in nu-402 trient uptake for small biological molecules along with diffusion-mediated trans-403 port, especially for the strongly confined cell. However, it is evident from the 404 recorded videos of weakly and strongly confined cell suspensions that the trac-405 ers are advected more in the H10 than in the H30 chamber (Video 1 and Video 3). 406 Hence, we attempt to quantify the observed differences in fluid mixing through 407 correlation in flow velocity and displacement of passive tracers by the swimmers. 408 We calculate the normalised spatial velocity-velocity correlation function of 409 the flow fields, $C_{vv}(R) = \frac{\langle v(r) \cdot v(r+R) \rangle}{\langle v(r) \cdot v(r) \rangle}$ to estimate the enhancement of fluid 410 mixing in strong confinement (Figure 5A). The fluctuating flow field has a cor-411 relation length, $\lambda = 13.2 \,\mu m$ for the strongly confined H10 flow, which is 37.5% 412 higher than the weakly confined flow in $H = 30 \,\mu\text{m}$ ($\lambda = 9.6 \,\mu\text{m}$), even though the 413 cell is swimming very slowly in strong confinement. This observation is comple-414 mentary to the experiments of *Kurtuldu et al.* (2011) where enhanced mixing is 415

observed for active CR suspensions in 2D soap films compared to those in 3D 116 unconfined fluid (Leptos et al., 2009). In their case, the reduced spatial dimen-417 sion leads to long-ranged flow correlations due to the stress-free boundaries (the 418 force-dipolar flow reduces from $v \sim r^{-2}$ in 3D to $v \sim r^{-1}$ in 2D). In our case, strong 419 confinement reduces the force-dipolar swimmer in H30 to a force-monopole one 420 in H10 (as shown in the previous section). This leads to longer correlation length 421 scales in the flow velocity, which implies an increased effective diffusivity (scaling, 422 $\sim V_{rms}\lambda$ for a velocity field with RMS value V_{rms}) of the fluid particles on time scales 123 $\gg \lambda/V_{rmst}$ in strong confinement. 424

Next, we measure the displacement of the passive tracer particles when a 425 single swimmer passes through the field of view ($179 \,\mu m \times 143 \,\mu m$) in our experi-426 ments. The H30 swimmers are fast and therefore pass through this field of view 427 in $\sim 1 - 1.4$ s (Figure 5B), whereas the slow-moving H10 swimmers stay in the 428 field of view for the maximum recording time of ~ 8 s (*Figure 5C*). As the swim-429 mer moves within the chamber, it perturbs the tracer particles. The trajectories 430 of these tracer particles involve both Brownian components and large jumps in-431 duced by the motion and flow field of these swimmers. We colour code the tracer 432 trajectories based on their maximum displacement, Δr_{treet} during a fixed lag time 433 of $\Delta t = 0.2$ s (~10 flagellar beat cycles) (*Figure 5*B and C). The tracer trajectories 434 close to the swimming path of the representative H30 swimmer (black dashed ar-435 row) are mostly advected by the flow whereas those far away from the cell involve 136 mostly Brownian components (Figure 5B). However, a majority of the tracers in 437 the full field of view are perturbed due to the H10 flow, those in the close vicinity 438 being mostly affected (*Figure 5C*). Their advective displacements are larger than 439 that of the tracers due to H30 flow (see the colour bar below). 440

We define the spatial range to which a swimmer motion advects the tracers 441 – radius of influence, R_{ad} — to be approximately equal to the lateral distance 442 from the cell's swimming path (black dashed arrow) where the tracer displace-443 ments decrease to $\sim 20\%$ of their maxima (dark orange trajectories). The region 444 of influence for the H30 cell is a cylinder of radius $R_{ad} \approx 15 \,\mu\text{m}$ with the cell's 445 swimming path as its axis (Figure 5B) and that for the H10 cell is a sphere of ra-44F dius $R_{ad} \approx 35 \,\mu\text{m}$ centred on the slow swimming cell's trajectory (*Figure 5*C). That 447 is, the radius of influence of the H10 flow is higher than the H30 one, which cor-448

roborates the longer velocity correlation length scale in strong confinement. We ллс also measure the mean-squared displacement (MSD) of the tracers to quantify 450 the relative increment in the advective transport of the H10 flow with respect to 451 the H30 one. We calculate the MSD of approximately 500 tracers in the whole 452 field of view for each video where a single cell is passing through it and then en-453 semble average over 6 such videos (Figure 5-Figure Supplement 1). These plots 454 with a scaling $\langle \Delta r_{trer}^2 \rangle \propto \Delta t^{\alpha}$ show a higher MSD exponent in H10 ($\alpha \simeq 1.55$) than 455 H30 ($\alpha \simeq 1.25$) indicating enhanced anomalous diffusion in strong confinement. 156 Together, Figure 5 shows that the fluid is advected more in strong confinement 457 leading to enhanced fluid mixing and transport. In other words, the opposite 458 vortical flows driven by flagellar beating in strong confinement help in advection-150 dominated dispersal of nutrients, air and CO₂ in the surrounding fluid, thereby 460 aiding the organism to avail itself of more nutrients for growth and metabolism. 461

462 **Discussion**

Our results show that a prototypical puller-type of microswimmer like CR, when 463 squeezed between two solid walls with a gap that is narrower than its size, has a 464 remarkedly different motility and flow field from those of a bulk swimmer. In this 465 regime of strong confinement, the cells experience a non-hydrodynamic contact 466 friction that is large enough to decrease their swimming speed by 96%. Conse-467 quently, their effect on the fluid is dominantly through the flagella, which pull 468 the fluid towards the organism and therefore, the major vortices in the associ-46° ated flow field have vorticity opposite to that observed in bulk or weak confine-470 ment. This leads to an increased mixing and transport through the flow in strong 471 confinement. These experimental results, which arise due to mechanical friction 172 from the walls and not due to any behavioural change, establish that confine-173 ment not only alters the hydrodynamic stresses but also modifies the swimmer 474 motility which in turn impacts the fluid flows. This coupling between confinement 475 and motility is typically ignored in theoretical studies because the focus tends to 476 be on the effect of confining geometry on flow-fields induced by a given set of 477 force-generators (Brotto et al., 2013; Mathijssen et al., 2016), which is appropri-478 ate for weak confinement, whereas strong confinement alters the complexion of 47¢ forces generating the flow. Recent experimental reports have not observed the 480

effect we discuss because they confine CR in chambers of height greater than the cell size ($D/H \leq 0.7$) (*Jeanneret et al., 2019*) where the stresses are mostly hydrodynamic and therefore their theoretical model is force-free and different from ours (*Appendix 1.5*).

Our theoretical approach of using two like-signed Brinkman Stokeslets local-485 ized with a Gaussian spread on the propelling appendages can also be easily 486 utilised to analyze flows of a dilute collection of strongly confined swimmers 487 (Appendix 1.6 and Appendix 1—Figure 2). Notably, the force-monopolar flow field 188 of the strongly confined CR is similar to that of tethered microorganisms like Vorti-489 cella within the slide-coverslip experimental setup (Pepper et al., 2010; O'Malley, 490 2011). Therefore, our effective 2D theoretical model involving Brinkman Stokeslet /01 is applicable to these contexts as well. However, one needs to account for the dif-492 ferences in ciliary beating (two-ciliary flow for CR whereas multi-ciliated metachronal 493 waves for Vorticella) for a comprehensive description of the flow field closer to the 494 organism (Pepper et al., 2010; Ryu et al., 2016). 495

We note that even though CR is known to glide on liquid-infused solid sub-496 strates through flagella-mediated adhesive interactions (Sasso et al., 2018), it has 497 recently been shown that the strength of flagellar adhesion is sensitive to and 498 switchable by ambient light (Kreis et al., 2018). Consequently, it is likely that 499 CR in its natural habitat of rocks and soils would also utilise swimming in ad-500 dition to gliding. Our quantitative analysis shows that despite the higher fric-501 tional drag due to the strongly confining walls, there is enhanced fluid mixing 502 due to the H10 flow field. That is, the inverse vortical flows driven by the flag-503 ellar propulsive thrust help in advection-mediated transport of nutrients to the 504 strongly confined microswimmer. This suggests that swimming is more efficient 505 than gliding for CR under strong confinement (especially in low-light conditions), 506 even though CR speeds are of the same order in both these mechanisms [$u_{glide} \sim$ 507 1 μ m/s (*Sasso et al., 2018*) and $u_{swim} \sim 4 \mu$ m/s]. We note that apart from the time-508 averaged flows, the oscillations produced in the flow (v^{osc}) due to the periodic 509 beating of the flagella can play a role in fluid transport and mixing for both the 510 H30 ($v_b \sim 55$ Hz, order of magnitude estimate of $v^{osc} \sim L \times 2\pi v_b \sim 3450 \,\mu$ m/s) and 511 H10 ($v_b \sim 52$ Hz, $v^{osc} \sim 3270 \,\mu\text{m/s}$) cells (*Guasto et al., 2010*; *Klindt and Friedrich*, 512 2015). 513

Finally, our experimental and theoretical methodologies are completely gen-514 eral and can be applied to any strongly confined microswimmer, biological or 515 synthetic from individual to collective scales. Specifically, our robust and efficient 516 description using point or Gaussian forces in a guasi-2D Brinkman equation is 517 simple enough to implement and analyze confined flows in a wide range of ac-518 tive systems. We expect our work to inspire further studies on biomechanics 519 and fluid mixing due to hard wall confinement of concentrated active suspen-520 sions (Kurtuldu et al., 2011: Pushkin and Yeomans, 2014: lin et al., 2021). These 521 effects can be exploited in realizing autonomous motion through microchan-522 nel for biomedical applications and in microfluidic devices for efficient control, 523 navigation and trapping of microbes and synthetic swimmers (Park et al., 2017: 524 Karimi et al., 2013: Temel and Yesilvurt, 2015). 525

526 Materials and Methods

527 Surface modification of microspheres and glass surfaces

CR cells are synchronously grown in 12:12 hour light:dark cycle in Tris-Acetate-528 Phosphate (TAP+P) medium. This culture medium contains divalent ions such 520 as Ca^{2+} , Mg^{2+} , SO_4^{2-} which decrease the screening length of the 200 nm nega-530 tively charged microspheres, thereby promoting inter-particle aggregation and 531 sticking to glass surfaces and CR's flagella. Therefore, the sulfate latex micro-532 spheres (S37491, Thermo Scientific) are sterically stabilised by grafting long poly-533 mer chains of polyethylene glycol (mPEG-SVA-20k, NANOCS, USA) with the help of 534 a positively charged poly-L-lysine backbone (P7890, 15-30kDa, Sigma) (Mondal et al., 535 2020). In addition, the coverslip and slide surfaces are also cleaned and coated 536 with polyacrylamide brush to prevent non-specific adhesion of microspheres and 537 flagella to the glass surfaces, prior to sample injection (Mondal et al., 2020). 538

Sample imaging

Cell suspension is collected in the logarithmic growth phase within the first 2-3 hours of light cycle and re-suspended in fresh TAP+P medium. After 30 minutes of equilibration, the cells are injected into the sample chamber. The sample chamber containing cells and tracers is mounted on an inverted microscope (Olympus IX83/IX73) and placed under red light illumination (> 610 nm) to pre-

vent adhesion of flagella (Kreis et al., 2018) and phototactic response of CR (Sineshcheko 545 2002). We let the system acclimatize in this condition for 40 minutes before 546 recording any data. All flow field data, flagellar waveform and cellular trajectory 547 (except for Figure 2A) are captured using a 40X phase objective (Olympus, 0.65 548 NA, Plan N, Ph2) coupled to a high speed CMOS camera (Phantom Miro C110, 549 Vision Research, pixel size = 5.6 µm) at 500 frames/s. As CR cells move faster in 550 $H = 30 \,\mu\text{m}$ chamber, a 8.2 second long trajectory cannot be captured at that mag-551 nification. So we used a 10X objective in bright field (Olympus, 0.25 NA, PlanC N) 552 connected to a high speed camera of higher pixel length (pco.1200hs, pixel size 553 = 12 µm) at 100 frames/s to capture 8.2 s long trajectories of H30 cells (*Figure 2*A). 554 Our observations are consistent across CR cultures grown on different days 555 and cultures inoculated from different colonies of CR agar plates. We have pre-556 pared at least 15-18 samples of dilute CR suspensions from 8 different days/batches 557 of cultures, each for chambers of height 10 and 30 µm. Our imaging parameters 558 remain same for all observations. We also use the same code, which is verified 559 from standard particle tracking videos, for tracking all the cells. We modify the 560 cell tracking code to track the tracer motion for calculating the flow-field data. 561

562 Height measurement of sample chamber

We use commercially available double tapes of thickness 10 and 30 µm (Nitto 563 Denko Corporation) as spacer between the glass slide and coverslip. To measure 564 the actual separation between these two surfaces, we stick 200 nm microspheres 565 to a small strip (18 mm × 6 mm) on both the glass surfaces by heating a dilute solu-566 tion of microspheres. Next, we inject immersion oil inside the sample chamber to 567 prevent geometric distortion due to refractive index mismatch between objective 568 immersion medium and sample. The chamber height is then measured by focus-569 ing the stuck microspheres on both surfaces through a 60X oil-immersion phase 570 objective (Olympus, 1.25 NA). We find the measured chamber height for the 10 571 μ m spacer to be 10.88 \pm 0.68 μ m and for the 30 μ m spacer to be 30.32 \pm 0.87 μ m, 572 from 8 different samples in each case. 573

574 Particle Tracking Velocimetry (PTV)

The edge of a CR cell body appears as a dark line (*Figure 1*C to E) in phase contrast 575 microscopy and is detected using ridge detection in Imagel (Wagner and Hiner, 576 2017). An ellipse is fitted to the pixelated CR's edge and the major axis vertex 577 in between the two flagella is identified through custom-written MATLAB codes 578 (refer to source code file). The cell body is masked and the tracers' displace-570 ment in between two frames (time gap, 2 ms) are calculated in the lab frame 580 using standard MATLAB tracking routines (Blair and Dufresne, 2008). The veloc-581 ity vectors obtained from multiple beat cycles are translated and rotated to a 582 common coordinate system where the cell's major axis vertex is pointing to the 583 right (Figure 3A.C). Outliers with velocity magnitude more than six standard de-584 viations from the mean are deleted. The resulting velocity vectors from all beat 585 cycles (including those from different cells in $H = 30 \, \text{um}$) are then placed on a 586 mesh grid of size $2.24 \,\mu\text{m} \times 2.24 \,\mu\text{m}$ and the mean at each grid point is computed. 587 The gridded velocity vectors are then smoothened using a 5×5 averaging filter. 588 Furthermore, for comparison with theoretical flow, the x and y components of 580 the velocity vectors are interpolated on a grid size of $1 \times 1 \,\mu\text{m}^2$. Streamlines are 590 plotted using the 'streamslice' function in MATLAB. 591

592 Trajectory tortuosity

Tortuosity characterizes the number of twists or loops in a cell's trajectory. It is 593 given by the ratio of arclength to end-to-end distance between two points in a 594 trajectory. We divide each trajectory into segments of arc-length \approx 20 µm. We 595 calculate the tortuosity for individual segments and find their mean for each tra-596 jectory. We consider the trajectories of all cells whose mean speed > 1 μ m/s and 597 are imaged at 500 frames/s through 40X objective for consistency. There were 52 598 H30 cells, 35 H10 Wobblers and 23 H10 Synchronous cells which satisfied these 599 conditions and the data from these cells constitute Figure 2G. 600

⁶⁰¹ Root Mean Square Deviation (RMSD)

The match between experimental and theoretical flow fields is quantified by the root-mean-square deviation (RMSD) of their velocities in the normalised scale (v/v_{max}) . $RMSD = \sqrt{\sum_{j=1}^{NG} (v_j^{\text{expt}} - v_j^{\text{th}})^2 / NG}$, where v_j^{expt} and v_j^{th} are the experi-

- ⁶⁰⁵ mental and theoretical values of the velocity fields at the *j*-th grid point, respec-
- tively, and NG is the total number of grid points. We calculate RMSD in the x and
- $_{607}$ y components of the flow velocity i.e., in v_x and v_y respectively, for a comparison
- ⁶⁰⁸ of the vector nature of the flow fields. This is because the signed magnitudes of
- v_{x} and v_{y} determine the vector direction of the flow. We also calculate RMSD in

the flow speed ($|v| = [v_x^2 + v_y^2]^{1/2}$) to compare their scalar magnitudes.

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Appendix 1

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1. Power dissipated through the flow fields

In low-Reynolds-number flows, the power P generated by a microswimmer is dissipated through the induced flow fields as $P = 2\eta \int_V (\Gamma : \Gamma) dV$ (*Guasto et al., 2010*). Here, η is the fluid viscosity, $\Gamma = \frac{1}{2} [\nabla v + (\nabla v)^T]$ is the fluid strain rate due to gradients in the flow velocity v_i and the integral is over the quasi-2D chamber of height *H*. Roughly, for flows in bulk or in 2D fluid films, the velocity gradient along the chamber height is negligible and only the 2×2 part of Γ corresponding to directions in the plane perpendicular to the confinement direction has non-negligible components (Guasto et al., 2010). This is not true in our case because the rigid boundaries act as momentum sinks, imposing a significant gradient in the fluid flow along the confinement direction *z*. Since the flow velocity varies as $v(x, y, z) = v^{0}(x, y) \cos(\pi z/H)$ (refer to Figure 4-Figure Supplement 1 and associated main text), the norm-squared strain rate tensor for hard-wall confined flows is given by Γ : $\Gamma = (\Gamma : \Gamma)^{\text{bulk}} + \frac{(\pi v^0)^2}{2H^2} \sin^2\left(\frac{\pi z}{H}\right)$ where $(\mathbf{\Gamma}:\mathbf{\Gamma})^{\text{bulk}} = (\partial_x v_x)^2 + \frac{1}{2}(\partial_y v_x + \partial_x v_y)^2 + (\partial_y v_y)^2 \text{ and } \mathbf{v}^0 = (v_x, v_y) \text{ is the flow pro$ file in the swimmer's x - y plane that is experimentally measured in **Figure 3**. We calculate the viscous power dissipation from the beat-averaged flow fields of CR to be $P^{30} = 0.78 \,\text{fW}$ in weak confinement and $P^{10} = 1.05 \,\text{fW}$ in strong confinement. These values are of the same order for both types of confinement and also to that measured for CR in thin fluid films [P_{mean flow} in Fig. 4a of *Guasto et al.* (2010)].

2. Comparison of our experimental flow data in strong confinement with Liron & Mochon's theoretical solution

The far-field solution of Liron & Mochon for a parallel Stokeslet, *F* located midway between two no-slip plates is given by $v_i^{LM}(r) = Q^{SD} \left(-\frac{\delta_{ij}}{r^2} + \frac{2r_i r_j}{r^4} \right) F_j$, which is equivalent to that of a 2D source dipole of strength $Q^{SD} = \frac{3H}{8\pi\eta} \frac{z}{H} \left(1 - \frac{z}{H} \right)$ (*Liron and Mochon, 1976*).

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Appendix 1 Figure 1. Theoretically computed flow field in confinement from Liron & Mochon's formula. (A) Theoretically computed flow field using Liron & Mochon's solution for 2-Stokeslet model in 2D. The red arrows at $(6,\pm11) \mu m$ denote the position of the Stokeslets. The colorbar represents flow magnitude normalised by its maximum, v_{nor} . Scale bar, $10 \mu m$. (B) Comparison between normalised experimental flow of a cell swimming in $H = 10 \mu m$ (*Figure 3*C) and Liron & Mochon's theoretical flow field (A) along representative radial distances, r, from the cell centre as a function of polar angle; $r (\mu m) = 7$ (yellow), 13 (blue), 20 (magenta), 30 (green). (C) Flow magnitude variation along 4 directions as indicated by separate colors in the *middle* inset [lateral to vortex (blue), lateral to cell centre (yellow), anterior (red), posterior (grey)] for the normalised experimental (symbols) and theoretical (solid lines) velocity fields in *Figure 3*C and *Appendix 1—Figure 1*A, respectively. Except for the theoretical speed along the vortex direction (blue), others are negligible compared to the experiment as shown in the *rightmost* inset, which is a semilog plot of (C) in the *y*-axis.

As we have shown that the hydrodynamic cell drag is negligible to the flagellar thrust, the cell-body drag is insignificant and the observed flow field is mostly due to flagellar thrust. We, therefore, superpose Liron & Mochon's solution for two flagellar forces and obtain the flow in *Appendix 1—Figure 1*A. The streamlines of the '2-Stokeslet Liron & Mochon flow' are qualitatively similar to that of the experiment (*Figure 3*C). However, the 2-Stokeslet theoretical flow of Liron & Mochon decays much more rapidly than the experimental one and does not capture the experimental flow variation as shown in *Appendix 1—Figure 1*B,C. Notably, there is no signature of vortex position lateral to the forcing point i.e., no minimum in the blue solid curve in *Appendix 1—Figure 1*C because v^{LM} is singular. Therefore, this far-field

limit of the theoretical model is insufficient to describe the near-field flow variation, positions of vortices and other flow features of the strongly confined flow accurately. The root mean square deviation (RMSD) in v_x , v_y & |v| between the experimental flow of a H10 cell (*Figure 3*C) and 2-Stokeslet Liron & Mochon's flow is 25.9%, 16.8% and 30.8%, respectively (see Materials and Methods for RMSD definition).

3. Inverse Fourier transform of the quasi-2D Brinkman equation in Fourier space

The quasi-2D Brinkman equation in Fourier space, *Equation 2* in the main text, is

$$\boldsymbol{v}_{k} = \frac{\boldsymbol{O}_{k} \cdot \boldsymbol{F}}{\eta \left(k^{2} + \frac{\pi^{2}}{H^{2}}\right)} \tag{A1}$$

Here, the orthogonal projection operator in polar coordinates (k, θ) is

$$\boldsymbol{O}_{\boldsymbol{k}} = 1 - \hat{\boldsymbol{k}}\hat{\boldsymbol{k}} = \begin{bmatrix} 1 - \hat{\boldsymbol{k}}_{x}^{2} & -\hat{\boldsymbol{k}}_{x}\hat{\boldsymbol{k}}_{y} \\ -\hat{\boldsymbol{k}}_{y}\hat{\boldsymbol{k}}_{x}^{2} & 1 - \hat{\boldsymbol{k}}_{y}^{2} \end{bmatrix} = \begin{bmatrix} \sin^{2}\theta & -\sin\theta\cos\theta \\ -\sin\theta\cos\theta & \cos^{2}\theta \end{bmatrix}$$
(A2)

where θ is the angle between wave vector \mathbf{k} and x-axis. For Stokeslets/Gaussian forces pointing along x- direction only, as in our case, $F = \begin{bmatrix} F \\ 0 \end{bmatrix}$, therefore $O(\mathbf{k}) \cdot F = \begin{bmatrix} \sin^2 \theta \\ -\sin \theta \cos \theta \end{bmatrix} F.$

To compute the velocity field in real space, we inverse Fourier transform **Equation A1** in polar coordinates, by replacing the numerator as shown above

$$\boldsymbol{v}(\boldsymbol{r}) = \frac{1}{(2\pi)^2 \eta} \int e^{i\boldsymbol{k}\cdot\boldsymbol{r}} \begin{bmatrix} \sin^2 \theta \\ -\sin \theta \cos \theta \end{bmatrix} \frac{F \ kdkd\theta}{\left(k^2 + \frac{\pi^2}{H^2}\right)}$$
(A3)

In polar coordinates, the field points in the x - y plane are given by $(x, y) = (r \cos \phi, r \sin \phi)$, hence $\mathbf{k} \cdot \mathbf{r} = kr \cos(\theta - \phi)$. Thus, the fluid velocity field is

$$\begin{bmatrix} v_x \\ v_y \end{bmatrix} (r,\phi) = \frac{F}{4\pi^2 \eta} \int_0^{2\pi} d\theta \int_0^\infty dk \begin{bmatrix} \sin^2 \theta \\ -\sin \theta \cos \theta \end{bmatrix} \frac{k e^{ikr\cos(\theta-\phi)}}{\left(k^2 + \frac{\pi^2}{H^2}\right)}$$
(A4)

Let us change the θ integral from $(0, 2\pi) \rightarrow (-\pi/2 + \phi, \pi/2 + \phi)$, where $\cos(\theta - \phi) > 0$. For example, the θ integral for v_x changes as follows,

$$\int_{0}^{2\pi} \sin^2 \theta e^{ikr\cos(\theta-\phi)} d\theta = \int_{-\frac{\pi}{2}+\phi}^{\frac{\pi}{2}+\phi} \sin^2 \theta e^{ikr\cos(\theta-\phi)} d\theta + \int_{\frac{\pi}{2}+\phi}^{\frac{3\pi}{2}+\phi} \sin^2 \theta e^{ikr\cos(\theta-\phi)} d\theta$$
(A5)

Replacing $\theta \to \theta - \pi$ in the 2nd integral, the limits change as $(\pi/2 + \phi, 3\pi/2 + \phi) \to (-\pi/2 + \phi, \pi/2 + \phi)$, and the integrands $\sin \theta \to -\sin \theta$, $\cos \theta \to -\cos \theta$, $\cos(\theta - \phi) \to -\cos(\theta - \phi)$. Therefore, the 2nd integral in the above equation changes to $\int_{-\frac{\pi}{2}+\phi}^{\frac{\pi}{2}+\phi} \sin^2 \theta e^{-ikr\cos(\theta - \phi)} d\theta$. Hence, v_x 's θ integral becomes

$$\int_{0}^{2\pi} \sin^2 \theta e^{ikr\cos(\theta-\phi)} d\theta = 2 \int_{-\frac{\pi}{2}+\phi}^{\frac{\pi}{2}+\phi} \sin^2 \theta \cos[kr\cos(\theta-\phi)] d\theta$$
(A6)

Similarly, $\int_0^{2\pi} -\sin\theta\cos\theta e^{ikr\cos(\theta-\phi)}d\theta = 2\int_{-\frac{\pi}{2}+\phi}^{\frac{\pi}{2}+\phi} -\sin\theta\cos\theta\cos[kr\cos(\theta-\phi)]d\theta$. Thus the velocity field in polar coordinates is given by,

$$\begin{bmatrix} v_x \\ v_y \end{bmatrix} (r,\phi) = \frac{F}{2\pi^2 \eta} \int_{-\frac{\pi}{2}+\phi}^{\frac{\pi}{2}+\phi} d\theta \int_0^{\infty} dk \begin{bmatrix} \sin^2 \theta \\ -\sin \theta \cos \theta \end{bmatrix} \frac{k \cos[kr \cos(\theta - \phi)]}{\left(k^2 + \frac{\pi^2}{H^2}\right)}$$
(A7)

For Gaussian forces, the numerator just gets multiplied by $e^{-k^2\sigma^2/2}$. We perform these 2D integrals in MATLAB for a 20 × 23 XY grid, with *k* integral ranging from 0 to 100 to obtain the theoretical flow fields in this article.

The above integration takes 3 hours of computational time for 2 Stokeslets whereas it takes only 1 minute to compute the flow field for 2 Gaussian forces of $\sigma = 5 \,\mu\text{m}$ (*Processor:* Intel i7-4770 CPU with clock speed 3.4 GHz). Hence, we try to write a semi-analytical expression for the case of 2 Stokeslets. Let us consider $kr \cos(\theta - \phi) = p$ and $\frac{\pi r \cos(\theta - \phi)}{H} = q$. Then the *k*-integral changes from $\int_0^\infty \frac{k \cos[kr \cos(\theta - \phi)]}{(k^2 + \pi^2/H^2)} dk \rightarrow \int_0^\infty \frac{p \cos p}{p^2 + q^2} dp$. We rename this integral as I(q) and calculate it using the Exponential Integral, Ei [Eq. 3.723—5 of **Gradshteyn and Ryzhik (2007)**].

$$I(q) = \int_0^\infty \frac{p \cos p}{p^2 + q^2} \, dp = -\frac{1}{2} \left[e^{-q} \,\overline{\mathsf{Ei}}(q) + e^q \,\mathsf{Ei}(-q) \right] \tag{A8}$$

where,

$$\mathsf{Ei}(q) = -\int_{-q}^{\infty} \frac{e^{-m}}{m} \, dm = \int_{-\infty}^{q} \frac{e^{m}}{m} \, dm, \quad \text{for } q < 0 \tag{A9}$$

and to avoid the singularity for q > 0, it is defined by using the principal value of the integral as

$$\overline{\mathsf{Ei}}(q) = \int_{-\infty}^{-\epsilon} \frac{e^m}{m} \, dm + \int_{\epsilon}^{q} \frac{e^m}{m} \, dm, \text{ where } \epsilon > 0, \quad \text{for } q > 0 \tag{A10}$$

In our case q > 0, so we use **Equation A9** for calculating Ei(-q) and **Equation A10** for calculating $\overline{\text{Ei}}(q)$, wherein we use $\epsilon = 10^{-5}$. So, **Equation A7** reduces to

$$\begin{bmatrix} v_x \\ v_y \end{bmatrix} (r, \phi) = \frac{F}{2\pi^2 \eta} \int_{-\frac{\pi}{2} + \phi}^{\frac{\pi}{2} + \phi} d\theta \begin{bmatrix} \sin^2 \theta \\ -\sin \theta \cos \theta \end{bmatrix} I(q)$$
(A11)

This method computes the flow field for 2 Stokeslets in 12 minutes on the same processor.

4. Swimmer based Péclet number

Generally, speed and length scales in the definition of Péclet number are given by the swimmer speed, *u*, and radius, *R* which we refer to as the swimmer based Péclet number, $Pe_c = uR/D_S$. By this definition, $Pe_c^{30} \approx 0.6$ and $Pe_c^{10} = 0.02$ for the weakly and strongly confined CR, respectively. However, we note that the flow field closer to the cell surface is dominated by the vortices lateral to the cell body (*Figure 3*A,C), whose magnitude is significantly higher than the swimmer speed for the strongly confined cell ($V/u \sim 11$), in contrast to that of the weakly confined cell ($V/u \sim 0.3$). Hence, the flow based Péclet number is more appropriate for describing the enhancement of mass transport of solutes due to the vortical flow fields generated by the flagella, particularly for the strongly confined cell ($H = 10 \mu m$). This is shown below (*Appendix 1—Table 1*) to be 100 times higher than the swimmer based Péclet number, whereas both definitions yield almost similar *Pe* for the weakly confined cell ($H = 30 \mu m$).

Appendix 1 Table 1. Flow based Péclet number calculation from the flow fields.

	$H = 30 \mu\text{m}$	$H = 10 \mu m$
Vortical flow speed, V (µm/s)	30	45
(<i>Figure 3</i> A,C)		(also frontal flow)
Vortical diameter, l_V (µm)	$2 \times 8.5 = 17$	$2 \times 20 = 40$
2 × vortex point distance (<i>Figure 3</i> B,D)		
$t_{\rm adv} = l_V/V$ (s)	0.57	0.8
$t_{\rm diff} = l_V^2 / D_S $ (s)	0.3	1.6
$Pe = t_{\text{diff}}/t_{\text{adv}} = l_V V/D_S$	0.5	2



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5. Comparison of our theoretical model of strongly confined flow with that of Jeanneret et al. (*Jeanneret et al., 2019*)

Jeanneret et al. provides an effective force-free 2D model for explaining the flow field of confined swimmers between 2 boundaries. They consider a force-free combination of 2D Brinkman Stokeslets along with a 2D source dipole to explain their experimental flows (*Jeanneret et al., 2019*). They use the analytical solution of *Pushkin and Bees* (*2016*) for their 2D Stokeslets with the permeability length $\lambda = H/\sqrt{12}$ (for the *z*-averaged flow in a Hele-Shaw cell of height *H*). They consider the conventional 3-Stokeslet model of CR where the flagellar thrust, distributed between 2 Stokeslets of strength $-F_S/2$ each at $(x_1, \pm y_1)$, is balanced by the cell drag of strength F_S at $(x_0, 0)$, all oriented along the direction of motion. Along with these force-free Stokeslets, they include the 2D source dipole of strength I_d at $(x_d, 0)$. Finally, they used this model with 6 free parameters $(F_S, x_0, x_1, y_1, I_d, x_d)$ to fit their experimentally observed flow fields of CR in confinements ranging from 14 to 60 µm.

However, our theoretical model consists of a 2D Brinkman Stokeslet because the strongly confined CR exerts a net force on the fluid due to the presence of strong non-hydrodynamic contact friction from the walls, unlike that of *Jeanneret et al.* (2019). This force-monopole is spatially distributed equally at the 2 flagellar positions, each with a Gaussian regularization to describe the strongly confined flow due to the H10 cell. The reason our theoretical approach is not the same as *Jeanneret et al.* (2019)

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is because there are two major differences in our experimental observations. First, we observe that the strongly confined H10 flow is mostly due to the flagellar motion with a 96% reduction in the cell's swimming speed, thanks to the static friction from the walls (compared to H30 cells), leading to the hydrodynamic cell-drag being nearly absent. This coupling between motility and confinement is not observed by Jeanneret et al. (2019), likely due to the slightly weak confinement ($D/H \leq 0.7$) produced by their experimental methodology, where the stresses present in the system are mostly hydrodynamic. It is therefore appropriate for them to use the force-free 3-Stokeslet theoretical model for CR (apart from the source dipole contribution) whereas in our case, the nearly absent hydrodynamic drag experienced by the cell body leads to a monopolar flow with only 2 Stokeslets (like-signed) localized with a Gaussian spread around the approximate flagellar positions. Second, the spinning motion of CR cells is restricted in our strongly confined H10 chambers unlike those in Jeanneret et al. (2019). They added the extra 2D source dipole in their theoretical model to account for both finite-sized effects of the cell body and spinning motion of the cells [explained in Fig. 1c of (Jeanneret et al., 2019)].

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6. Is the 2-Gaussian Brinkman model applicable to a collection of strongly confined pullers?

We analyze the fluid flow due to two strongly confined H10 Synchronous cells as a preliminary test for determining the applicability of our theoretical methodology to a collection of microswimmers. Specifically, we measure the beat averaged flow field of two synchronously beating cells which are separated by ~ 9 body diameters and approach each other head-on (*Appendix* 1—*Figure* 2A). Therefore, we linearly superpose the solution of the quasi-2D Brinkman equation for a pair of 2-Gaussian forces ($\sigma = 5 \mu m$) at the approximate flagellar positions of the two cells and obtain the resultant flow field (*Appendix* 1—*Figure* 2B). The position and direction of flow vortices along with the stagnation point in between the two cells match well between the experiment and theory. This suggests that linearly superposing 2-Gaussian Brinkman flows might be an adequate description for the flow field of a dilute collection of CRs.



Appendix 1 Figure 2. Flow fields due to two strongly confined H10 cells. (A) Experimentally measured flow field for two synchronous cells swimming in $H = 10 \,\mu$ m. This flow is averaged over ~ 30 beat cycles for each cell during which the cells move merely 0.05 times their respective body diameters ($D \sim 12.42 \,\mu$ m). The centre-to-centre distance between the swimmers is 8.75*D*. Black arrows on the cell bodies indicate their swimming direction. Solid black lines indicate the streamlines of the flow in lab frame. The colorbar represents flow magnitude, v. (**B**) Theoretically computed flow field by linearly superposing two 2-Gaussian Brinkman flow, one for each cell. The positions of the pair of 2-Gaussian forces at approximate flagellar positions are denoted by red arrows. The streamlines, vortex flows and stagnation point at the centre of the grid match qualitatively with the experimental one (A). The colorbar represents flow magnitudes normalised by its maximum, v_{nor} . Scale bars, 20 μ m.



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Figure 3-Figure supplement 1. Expected flow fields of a strongly confined CR using conventional theoretical approaches. (A) Theoretically computed *near-field flow* characteristics as expected from the screened version of the bulk flow field i.e., from the 3-Stokeslet model in $H = 10 \,\mu\text{m}$. The 3 Stokeslets denoted by red arrows represent the cell drag of strength +1 at (0,0) and flagellar thrust of strength -1/2 each at $(12,\pm10) \,\mu\text{m}$. This flow field is calculated using the quasi-2D Brinkman equation, which is introduced later in this article. (B) Theoretically predicted *far-field flow* of a microswimmer in confinement (but under the influence of hydrodynamic stresses only) which is that of a 2D source dipole oriented along the propulsion direction (denoted by red arrow) (*Mathijssen et al., 2016; Brotto et al., 2013*). The colorbars represent flow magnitudes normalised by their maximum, v_{nor} . Scale bars, 10 µm.



Figure 4–Figure supplement 1. Schematic of velocity profile along the confining direction. Schematic of flow profile along *z*-direction, $v(z) \sim \cos(\pi z/H)$, in a chamber of height *H* bounded by two solid walls.



Figure 4–Figure supplement 2. Comparison in the direction of flow fields between experiment and theory. Comparison of (A, C) v_x and (B, D) v_y between normalised experimental flow of the CR in $H = 10 \,\mu\text{m}$ (Figure 3C) with theoretical flow fields (Figure 4A) and (Figure 4C), respectively, along representative radial distances, r, from the cell centre as a function of polar angle. Plots for each r denote the flow components for those grid points which lie in the radial gap $(r, r + 1) \,\mu\text{m}; r (\mu\text{m}) = 7$ (yellow), 13 (blue), 20 (magenta), 30 (green).



Figure 4–Figure supplement 3. Theoretical flow field in weak confinement. (**A**) Theoretically computed flow field from 3-Gaussian forces (cell drag of strength +1 at (0,0), flagellar thrust of strength -1/2 each at $(12,\pm10) \mu$ m; all denoted by red arrows) using the quasi-2D Brinkman equation for $H = 30 \mu$ m at the z = 0 plane. The Gaussian standard deviation, σ for cell and flagellum are 3 and 5 μ m, respectively. The colorbar represents flow magnitude normalised by its maximum, v_{nor} . Scale bar, 10μ m. Comparison of (**B**) |v|, (**C**) v_x and (**D**) v_y between normalised experimental (**Figure 3**A) and theoretical flow field (A) of a cell swimming in $H = 30 \mu$ m along representative radial distances, r, from the cell centre as a function of polar angle. The convention used for polar angle is same as in **Figure 4**B/D. Plots for each r denote the flow magnitudes for those grid points which lie in the radial gap $(r, r + 1) \mu$ m; $r (\mu$ m) = 7 (yellow), 13 (blue), 20 (magenta), 30 (green).



Figure 5-Figure supplement 1. Mean squared displacement (MSD) of tracers. MSD of tracers, $\langle \Delta r_{trcr}^2 \rangle$, due to a representative CR cell swimming through the field of view in (**A**) $H = 30 \,\mu\text{m}$ and (**B**) $H = 10 \,\mu\text{m}$. Semi-transparent lines represent the MSD of ~500 tracers for each video where a single swimmer is passing through the field of view and the solid line with symbols denotes the average tracer MSD from 6 such videos. Black dashed lines indicate linear fit to the log-log data of average MSD vs lag-time (Δt) where α denotes the MSD exponent, $\langle \Delta r_{trcr}^2 \rangle \propto \Delta t^{\alpha}$.