Variable	Scaling equation	Description	Method for acquiring
<i>m</i> _{body}		Body mass	Measured extant bird data
			from literature (31 birds)
m _{pect}		Pectoralis mass (single	Measured extant bird data
		pectoralis)	from literature scaled
			isometrically to match body
			mass (exact match: 25 birds,
			close relative: 6 birds)
m _{wing}		Wing mass (single wing)	Measured extant bird data
			from literature (31 birds)
Iwing		Wing moment of inertia	Measured extant bird data
		(single wing)	from literature (27 birds) or
			determined based on scaling
			law reported in literature:
			Berg & Rayner 1995 (close
			relative: 4 birds)
r _{span}		Wingspan (distance from	Measured extant bird data
		shoulder joint to wingtip;	from literature (27 birds) or
		single wing)	measured extant bird data
			from literature scaled
			isometrically to match body
			mass (close relative: 4 birds)
r _{wing,cg}		Distance from shoulder	Measured extant bird data
		joint to center of gravity of	from literature (27 birds) or
		wing (single wing)	determined isometrically to
			match body mass (close
			relative: 4 birds)
Swing		Wing area (single wing)	Measured extant bird data
			from literature (27 birds) or
			measured extant bird data

Supplementary File 2a. Scaling analysis (Figure 7) parameter summary.

			from literature scaled
			isometrically to match body
			mass (close relative: 4 birds)
f		Wingbeat frequency	Measured extant bird data
			from literature (21 birds) or
			determined based on scaling
			law reported in literature:
			Berg & Rayner 1995 (10 birds)
m _{wing,i}		Wing mass distribution	Least-squares fit to match
		(point masses)	wing mass, inertia, and center
			of gravity data
Δt	$\propto f^{-1}$	Time step	Assumed to scale isometrically
$ec{\mathbf{F}}_{ ext{aero}}$	$\propto m_{ m body}$	Aerodynamic force	Assumed to scale isometrically
$^{N}\vec{v}_{wing}^{i}$	$\propto f \left \vec{\mathbf{r}}_{\text{span}} \right $	Wing velocity (distributed)	Assumed to scale isometrically
$^{N}\vec{v}_{body}$	∞1	Body velocity	Unchanged
X _{p,aero}	$=\left \vec{r}_{span}\right f$	Scaling parameter which	Derived (Eqn. S71)
		dictates the aerodynamic	
		power contribution \propto	
		wingtip speed	
$x_{ m m, aero}$	$=\left ec{r}_{span} ight $	Scaling parameter which	Derived (Eqn. S72)
		dictates the aerodynamic	
		moment contribution =	
		wingspan	
$X_{p,iner}$	$=\frac{I_{\text{wing}}}{m}f^3$	Scaling parameter which	Derived (Eqn. S73)
	$m_{\rm body}$	dictates the inertial power	
	$=\frac{m_{\text{wing}}}{m_{\text{wing}}}\left \frac{r_{\text{gyr}}}{ \vec{\mathbf{r}} }\right \left(f\left \vec{\mathbf{r}}_{\text{span}}\right \right)^{2}f$	contribution \propto (wing	
	‴body ([▲] span)	mass %) (wing radius of	
		gyration %) ² (wingtip	
		speed) ² (wingbeat	
		trequency)	

$x_{m,iner}$	$=\frac{I_{\text{wing}}}{f^2}$	Scaling parameter which	Derived (Eqn. S74)
	m _{body}	dictates the inertial	
	$=\frac{m_{\rm wing}}{\left(\frac{r_{\rm gyr}}{1-r_{\rm gyr}}\right)^2} \left(f\left \vec{\mathbf{r}}\right \right)^2$	moment contribution \propto	
	$m_{\text{body}} \left(\left \vec{\mathbf{r}}_{\text{span}} \right \right) \left(J \left \mathbf{r}_{\text{span}} \right \right)$	(wing mass %) (wing	
		radius of gyration %) ²	
		(wingtip speed) ²	

Supplementary File 2b. Scaling analysis parameters used for analyzing shifts in the timing of the pectoralis power distribution during the stoke (Figure 7D).

Variable	Scaling equation	Description	Method for acquiring
<i>m</i> _{body}		Body mass	Measured extant bird data
			from literature (17 birds)
$m_{ m wing}$		Wing mass (single wing)	Measured extant bird data
			from literature (1 birds) or
			measured extant bird data
			from literature scaled
			isometrically to match body
			mass (16 birds)
$\vec{\mathbf{r}}_{span}$		Wingspan (distance from	Measured extant bird data
		shoulder joint to wingtip;	from literature (3 birds) or
		single wing)	measured extant bird data
			from literature scaled
			isometrically to match body
			mass (14 birds)
f		Wingbeat frequency	Measured extant bird data
			from literature (17 birds)
EMG _{start}		Start of electrical	Measured extant bird data
		activation of pectoralis	from literature (17 birds)
		(stroke %)	
EMG _{end}		End of electrical activation	Measured extant bird data
		of pectoralis (stroke %)	from literature (17 birds)
F _{pect,max}		Max force generated by	Measured extant bird data
		pectoralis (stroke %)	from literature (12 birds)
Iwing		Wing moment of inertia	Determined based on scaling
		(single wing)	law reported in literature:
			Berg & Rayner 1995 (17
			birds)

$x_{\rm p,iner} / x_{\rm p,aero}$	$= x_{m,iner} / x_{m,aero}$	Scaling parameter which	Derived
	$=\frac{I_{\text{wing}}}{I_{\text{wing}}}f^2$	dictates the aerodynamic	
	$m_{\rm body} \left \vec{r}_{span} \right ^{J}$	power contribution \propto	
	$=\frac{m_{\rm wing}}{m_{\rm body}} \left(\frac{r_{\rm gyr}}{\left \vec{\mathbf{r}}_{\rm span}\right }\right)^2 \left(f\left \vec{\mathbf{r}}_{\rm span}\right \right) f$	wingtip speed	